

3) a) Vorlesung 12.4 // SL 17

$$L(w; x_n, t)_{n=1, \dots, 5}$$

$$= \sum_{n=1}^5 \left(\underline{t_n} w^T \phi(x_n) - \ln(1 + \exp(w^T \phi(x_n))) \right)$$

An den Trainingsdatensatz

$$\{ \overset{x_1 \ x_2 \ t}{\underline{(1, 3, 0)}, \underline{(2, 4, 0)}, \underline{(4, 1, 0)}, \underline{(3, 1, 1)}, \underline{(4, 2, 1)}} \in \mathbb{R}^2 \times \{0, 1\} \}.$$

$$\begin{aligned} &= \sum_{n=1}^5 \left(t_n (w_0 + w_1 x_1 + w_2 x_2) - \ln(1 + \exp(w_0 + w_1 x_1 + w_2 x_2)) \right) \\ &= -\ln(1 + \exp(w_0 + w_1 + 3w_2)) - \ln(1 + \exp(w_0 + 2w_1 + 4w_2)) \\ &\quad - \ln(1 + \exp(w_0 + 4w_1 + w_2)) + (w_0 + 3w_1 + w_2) \\ &\quad - \ln(1 + \exp(w_0 + 3w_1 + w_2)) + (w_0 + 4w_1 + 2w_2) \\ &\quad - \ln(1 + \exp(w_0 + 4w_1 + 2w_2)) \end{aligned}$$

b) Iterated Reweighted Least Squares (IRLS)

$$\underline{w}^{(t+1)} = \left(\underline{\Phi}^T R(w^{(t)}) \underline{\Phi} \right)^{-1} \cdot$$

$$\underline{\Phi} R(w^{(t)}) z(w^{(t)})$$

$$z(w^{(t)}) = \Phi w^{(t)} - R(w^{(t)})^{-1} \cdot (\pi(w^{(t)}) - t)$$

An den Trainingsdatensatz

$$\{ \overset{x_0}{(1, 3, 0)}, \overset{x_1}{(2, 4, 0)}, \overset{x_2}{(4, 1, 0)}, \overset{x_3}{(3, 1, 1)}, \overset{x_4}{(4, 2, 1)} \in \mathbb{R}^2 \times \{0, 1\} \}.$$

$$\Phi = \begin{pmatrix} \phi_0(x_1) & \phi_1(x_1) & \phi_2(x_1) \\ \phi_0(x_2) & \phi_1(x_2) & \phi_2(x_2) \\ \phi_0(x_3) & \phi_1(x_3) & \phi_2(x_3) \\ \phi_0(x_4) & \phi_1(x_4) & \phi_2(x_4) \\ \phi_0(x_5) & \phi_1(x_5) & \phi_2(x_5) \end{pmatrix} = \begin{pmatrix} \overset{x_0}{1} & \overset{x_1}{1} & \overset{x_2}{3} \\ 1 & 2 & 4 \\ 1 & 4 & 1 \\ 1 & 3 & 1 \\ 1 & 4 & 2 \end{pmatrix}$$

$$R(w^{(t)}) = \text{diag}(\pi(x_0) \cdot (1 - \pi(x_0)), \dots, \pi(x_5) \cdot (1 - \pi(x_5)))$$

$$a = w^T x$$

$$\pi(x) (1 - \pi(x)) = \frac{\exp(a)}{1 + \exp(a)} \left(1 - \frac{\exp(a)}{1 + \exp(a)} \right)$$

$$= \frac{\exp(a)}{1 + \exp(a)} \left(\frac{1}{1 + \exp(a)} \right)$$

$$= \frac{\exp(a)}{(1 + \exp(a))^2} = \frac{\exp(w^T x)}{(1 + \exp(w^T x))^2}$$

Startwert: $w^{(0)} = (0, 0, 0)^T$

$$\begin{aligned}\pi(x) \cdot (1 - \pi(x)) &= \frac{e(0)}{(1 + e(0))^2} \\ &= \frac{1}{2^2} = 1/4\end{aligned}$$

$$R(w^{(0)}) = \begin{pmatrix} 1/4 & & & & \\ & 1/4 & & & \\ & & 1/4 & & \\ & & & 1/4 & \\ & & & & 1/4 \end{pmatrix}$$

$$\pi(x) = \frac{\exp(w^T x)}{1 + \exp(w^T x)}$$

mit $w^{(0)} = (0, 0, 0)^T$

$$= \frac{e(0)}{1 + e(0)} = 1/2$$

$$\bar{\Phi} w^{(0)} R(w^{(0)})^{-1} \Pi(w^{(0)}) t$$

$$Z(w^{(0)}) = \begin{pmatrix} 1 & 1 & 3 \\ 1 & 2 & 4 \\ 1 & 4 & 1 \\ 1 & 3 & 1 \\ 1 & 4 & 2 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 4 & 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 4 & 0 & 0 \\ 0 & 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 & 4 \end{pmatrix} \left(\begin{pmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right) = \begin{pmatrix} -2 \\ -2 \\ -2 \\ 2 \\ 2 \end{pmatrix}$$

in II $w^{(1)} = \begin{pmatrix} -20/29 \\ 14/29 \\ -14/29 \end{pmatrix} \approx \begin{pmatrix} -0,69 \\ 0,48 \\ -0,48 \end{pmatrix}$

→ benutzt man um $R(w^{(1)})$

$\Pi(w^{(1)})$

→ $Z(w^{(1)})$

→ wieder in II einsetzen

$$w^{(2)} \rightarrow \begin{pmatrix} -0,574 \\ 0,61 \\ -0,61 \end{pmatrix}$$

$$w^{(3)} \approx \begin{pmatrix} -1,046 \\ 0,641 \\ -0,641 \end{pmatrix}, w^{(4)} \approx \begin{pmatrix} -1,05 \\ 0,642 \\ -0,642 \end{pmatrix}, w^{(5)} \approx \begin{pmatrix} -1,05 \\ 0,642 \\ -0,642 \end{pmatrix}, w^{(6)} \approx \begin{pmatrix} -1,05 \\ 0,642 \\ -0,642 \end{pmatrix}$$



$$\hat{w}_0 = -1,05 \quad // \quad \hat{w}_1 = 0,642, \hat{w}_2 = -0,642$$

$$\hat{\pi}(x) = \frac{\exp(\hat{w}_0 + \hat{w}_1 x_1 + \hat{w}_2 x_2)}{1 + \exp(\hat{w}_0 + \hat{w}_1 x_1 + \hat{w}_2 x_2)}$$

$$= \frac{\exp(-1,05 + 0,642 x_1 - 0,642 x_2)}{1 + \exp(-1,05 + 0,642 x_1 - 0,642 x_2)}$$

$$\hat{y}^*(x) = \begin{cases} C_1 & \text{für } \hat{\pi}(x) \leq 0,5 \\ C_2 & \text{für } \hat{\pi}(x) > 0,5 \end{cases} \quad \left| \begin{array}{l} B \rightarrow \text{yes} \\ \text{Klassifikator} \end{array} \right.$$

Dies ist äquivalent zu

$$\hat{y}^*(x) = \begin{cases} C_1 & \text{für } -1,05 + 0,642 x_1 - 0,642 x_2 \leq 0 \\ C_2 & \text{für } -1,05 + 0,642 x_1 - 0,642 x_2 > 0 \end{cases}$$

für neue Beobachtung (5, 0)

$$-1,05 + 0,642 \cdot 5 - 0,642 \cdot 0 > 0$$

→ Zuordnung zu Klasse C_2

Für Abbildung der Entscheidungsgrenze:

$$-1,05 + 0,642 x_1 - 0,642 x_2 = 0$$

$$x_2 = -1,635514 + x_1$$

